

Service-Oriented Architecture of Intelligent GIS

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Motivation and objectives

The requirements of end users to GIS is to obtain high quality solutions in the shortest possible time.

Most part of the end users tasks are highly complicated.

Users requirements to the tasks that are being solved change very quickly.

Users in their activities need to account for diverse factors.

Number of GIS users can reach hundreds and the system is expected to get adapted to each user requirements and provide necessary information space.

Modern Intellectual GIS being multilevel heterogeneous systems due to use of integrated means of artificial intelligence can propose an efficient solution.



Plan of report

- Introduction
- SOA concept for IGIS
- Common SOA of IGIS
 - Application services
 - Data base, knowledge base, ontology services
 - End users services
- Case study
- Conclusion

Applications' server



Java

ORACLE
WebLogic

bea weblogic

WebSphere
software



IBM

ORACLE
APPLICATION SERVER **10^g**

ORACLE

Sun
microsystems



SOA concept for IGIS



End users services

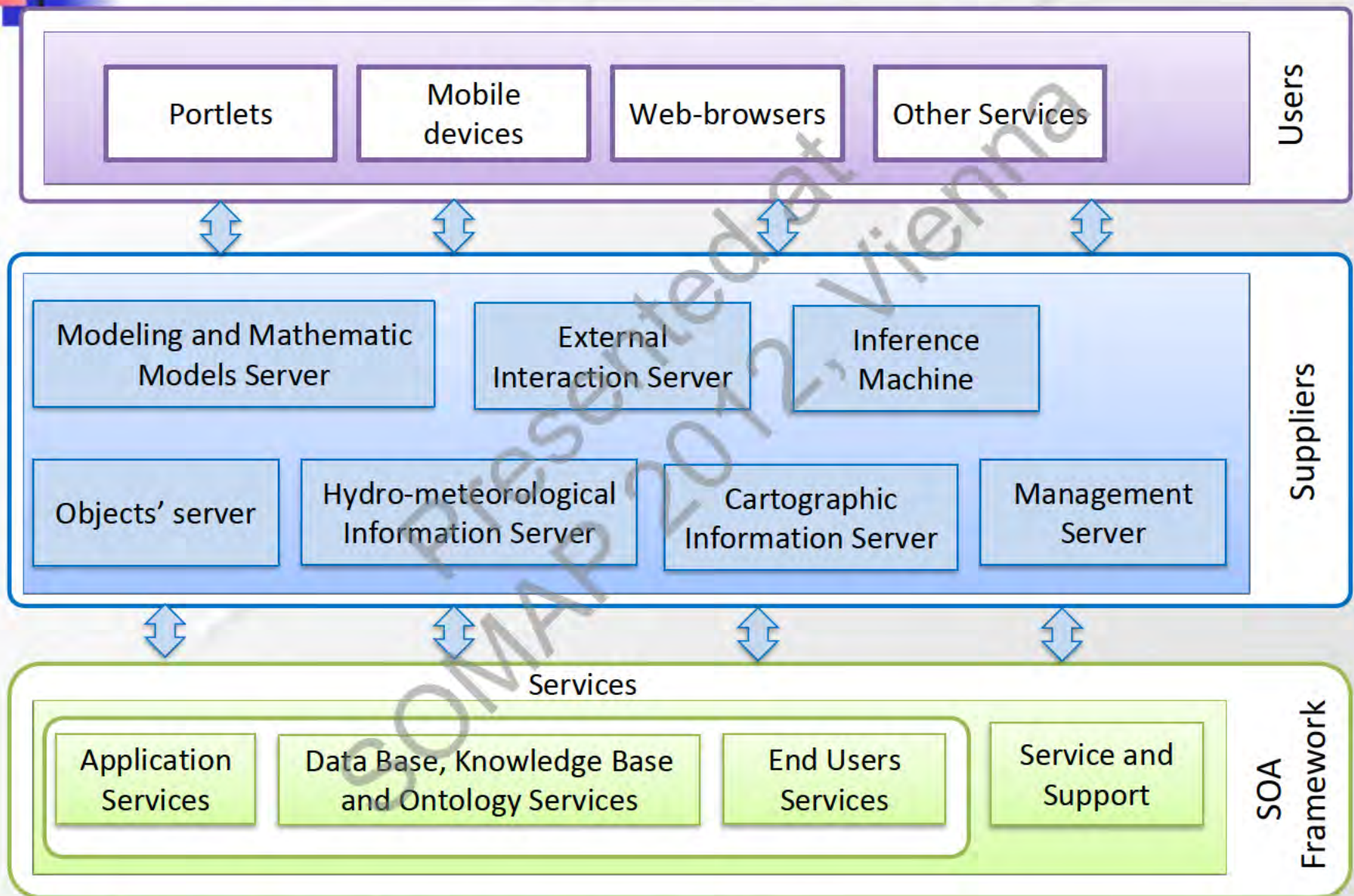


Applications services



Data bases & knowledge bases &
ontology services

Common SOA of IGIS



Cartographic information server



Services accessing spatial data of different formats including Shape, S57, SXF, OpenStreetLayer, VPF



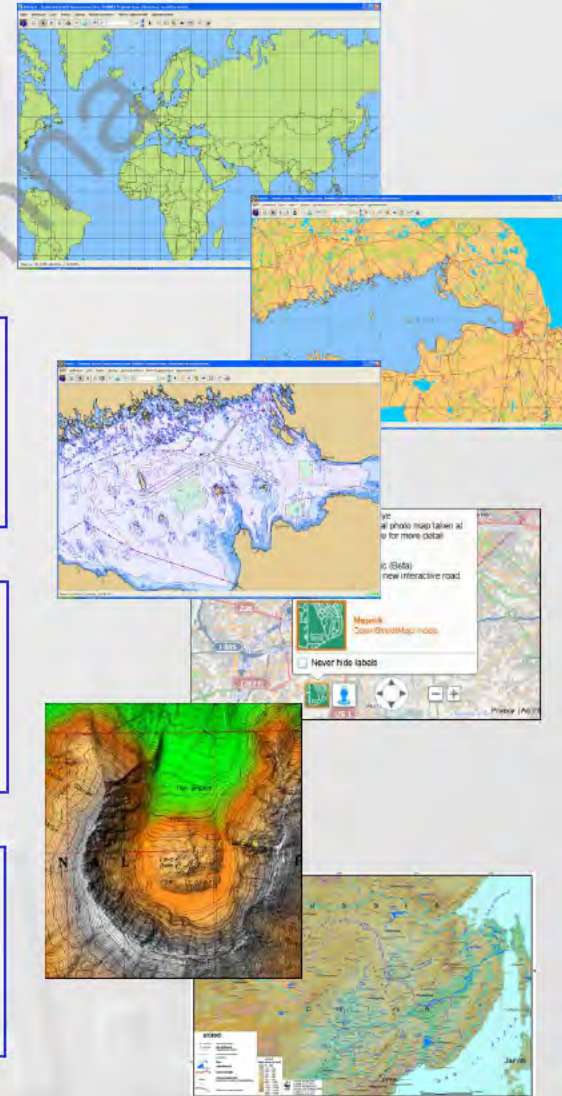
Services of geodesic functions for a given projection and Earth model



Services visualizing cartographic data



Services importing-exporting spatial data to/from different formats



Hydro meteorological information server



Service of selection and attuning the channel for receiving hydro meteorological information from a source via tcp, ftp protocols and e-mail



Service of filtering the flow of recipient information in accordance with the required types of hydro meteorological weather reports



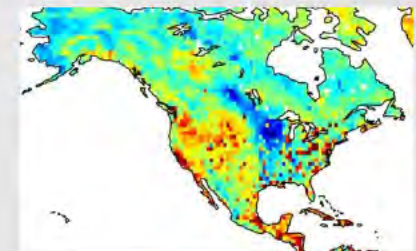
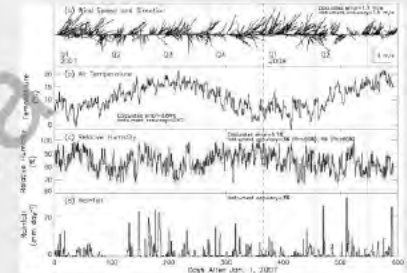
Service of sentence analysis of the recipient hydro meteorological information reports according to the international (World Weather Watch) and regional code forms



Service of decoding and storing the values of given meteorological parameters



Service of controlling the server's given operation processes



Modeling and mathematical models' server



Service of universal time



Services of mathematical problems (e.g., search theory, radio location, hydroacoustic)



Services of multilevel data processing



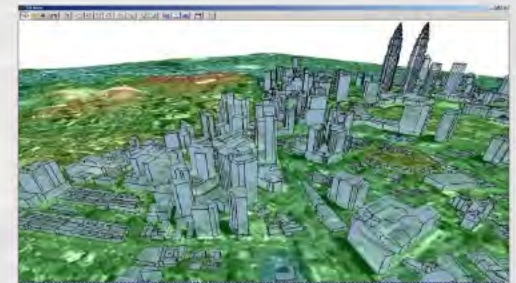
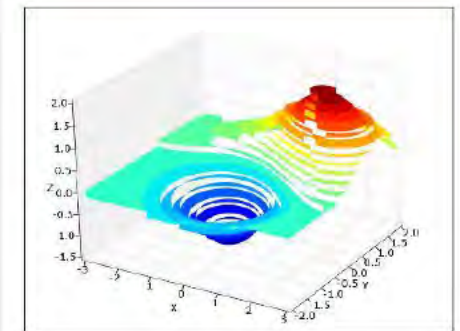
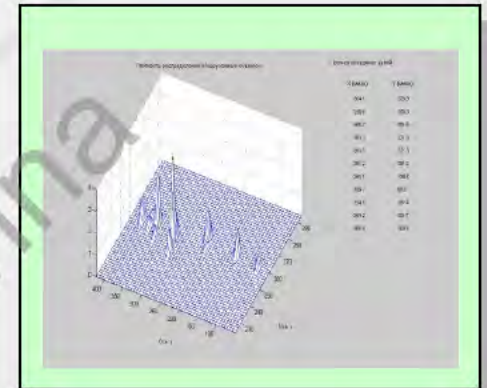
Services of simulation



Services of 3D results' representation



Services of objects' recognition and classification as well as tactical situations



Interaction with external systems server



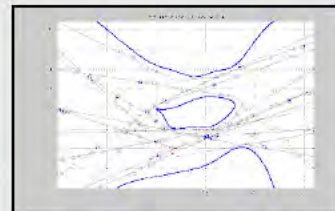
Service of receiving information from external mobile objects and systems (e.g., transportation monitoring systems, permanently functioning network of oceanographic stations based on drifting gauge-buoys (ARGO project) and other)



Service of receiving locations of sea and river vessels in the World Ocean based on AIS data



Service of receiving locations of aircrafts based on the data from Automatic Dependent Surveillance - Broadcast (ADS-B) system's transponders



Service of receiving locations of spacecrafts and calculation of their coverage zones based on open sources data, and a number of other services, being determined by a definite subject area



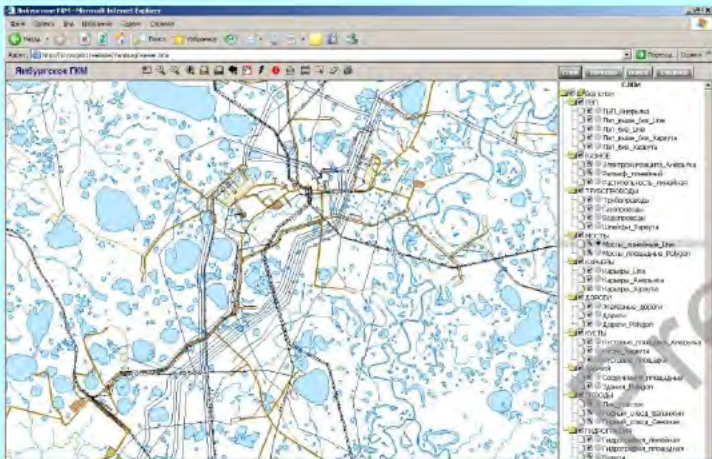
Administration (management) server

- ✓ Service of resources distribution
- ✓ Service managing the users' and other services access
- ✓ Service managing the IGIS tuning and operating modes
- ✓ Service of the IGIS operating journaling

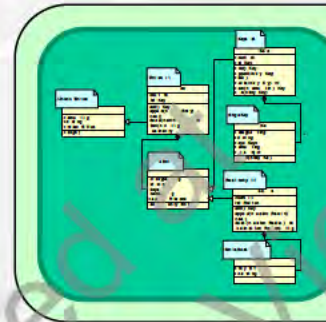


Objects server. Unified information model

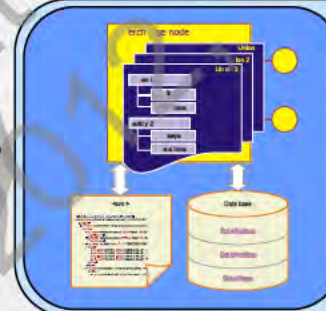
Dynamic unified information model



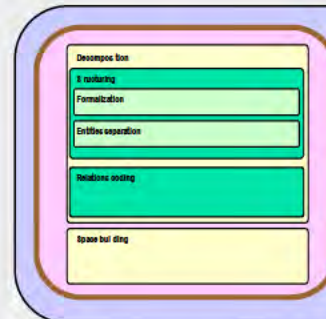
The dynamic information model represents a model of subject domain that during every moment of time contains data corresponding to the actual parameters of objects and environment in which they function.



The unified model of information presentation - the universal information and logical model providing to program components structure of entities, describing subject domain



The unified model of program interaction - the universal model providing to program components structure of entities containing in messages, transferred during information exchange.



Algorithm of information transformation to the unified model of program interaction, offering sequence of actions on information transformation from metamodels of borrowed components to unified model of information presentation

Information fusion concepts

+ Data Harmonization

Main properties of harmonization process is that the result of the process is easy to be received for a huge number of users.

+ Data Integration

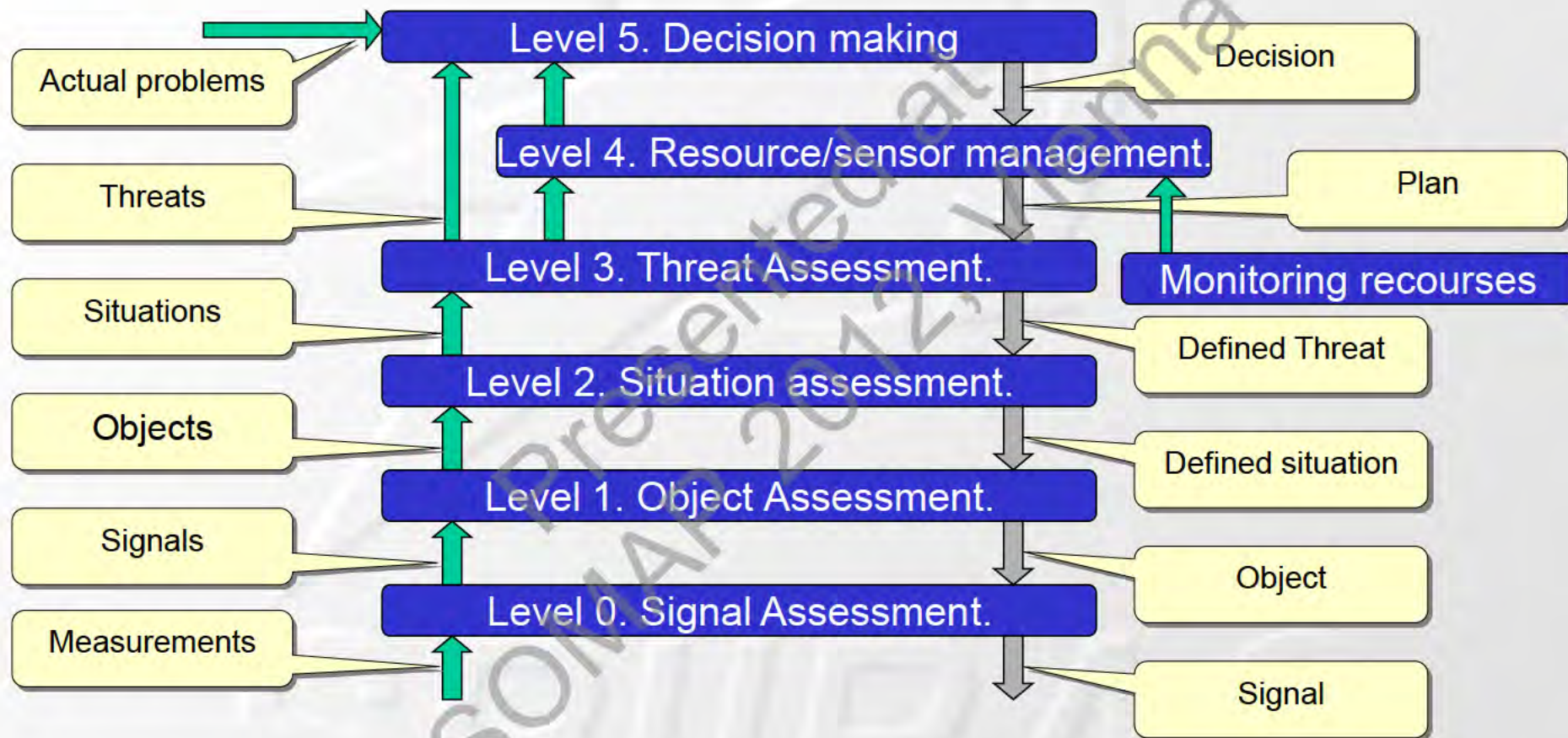
Main properties of DI is that the result of the process is oriented to the defined class of problem solving.

+ Data Fusion

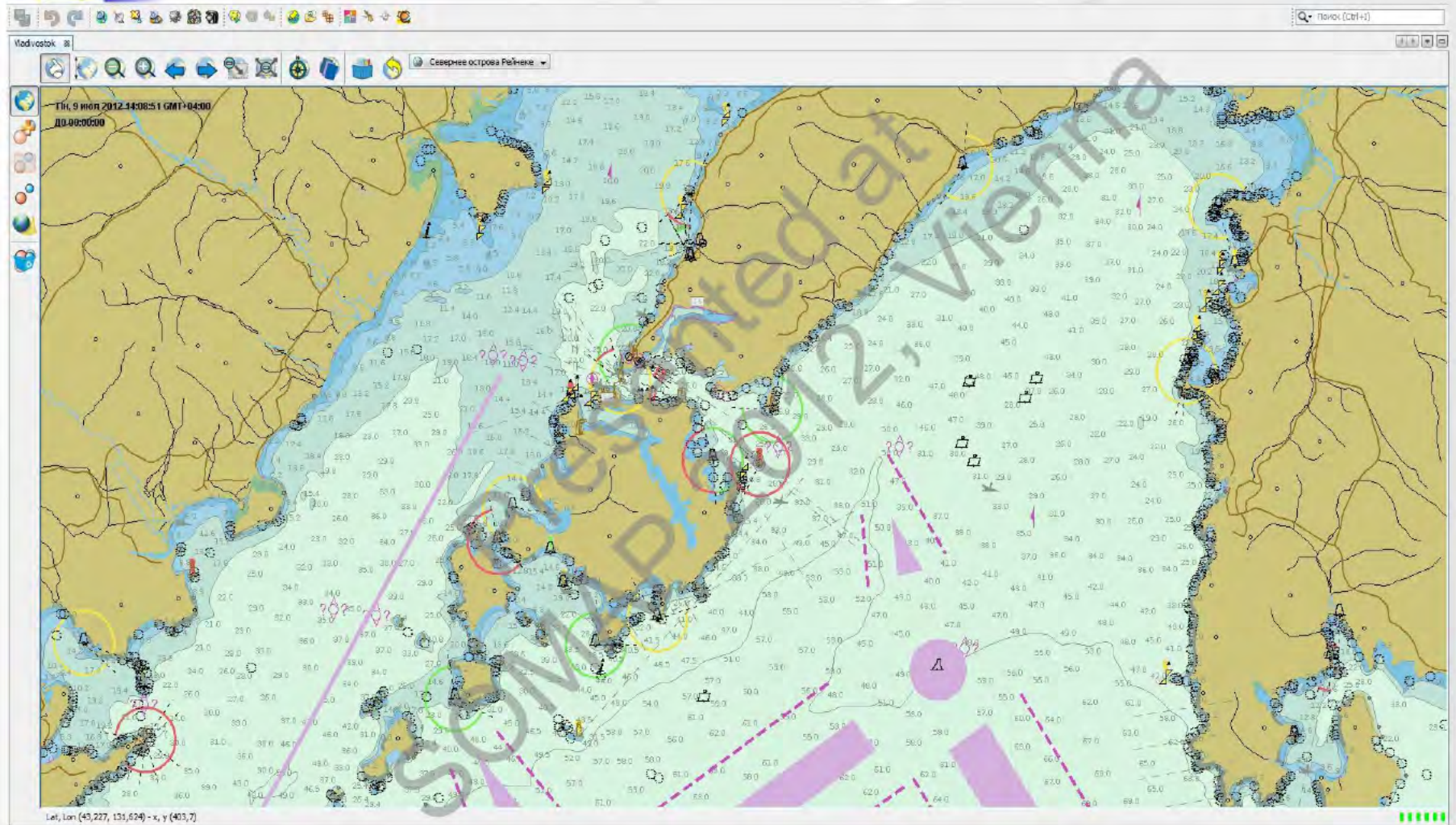
Main properties of Data Fusion is to obtain a new property of data and to reduce a volume of data.



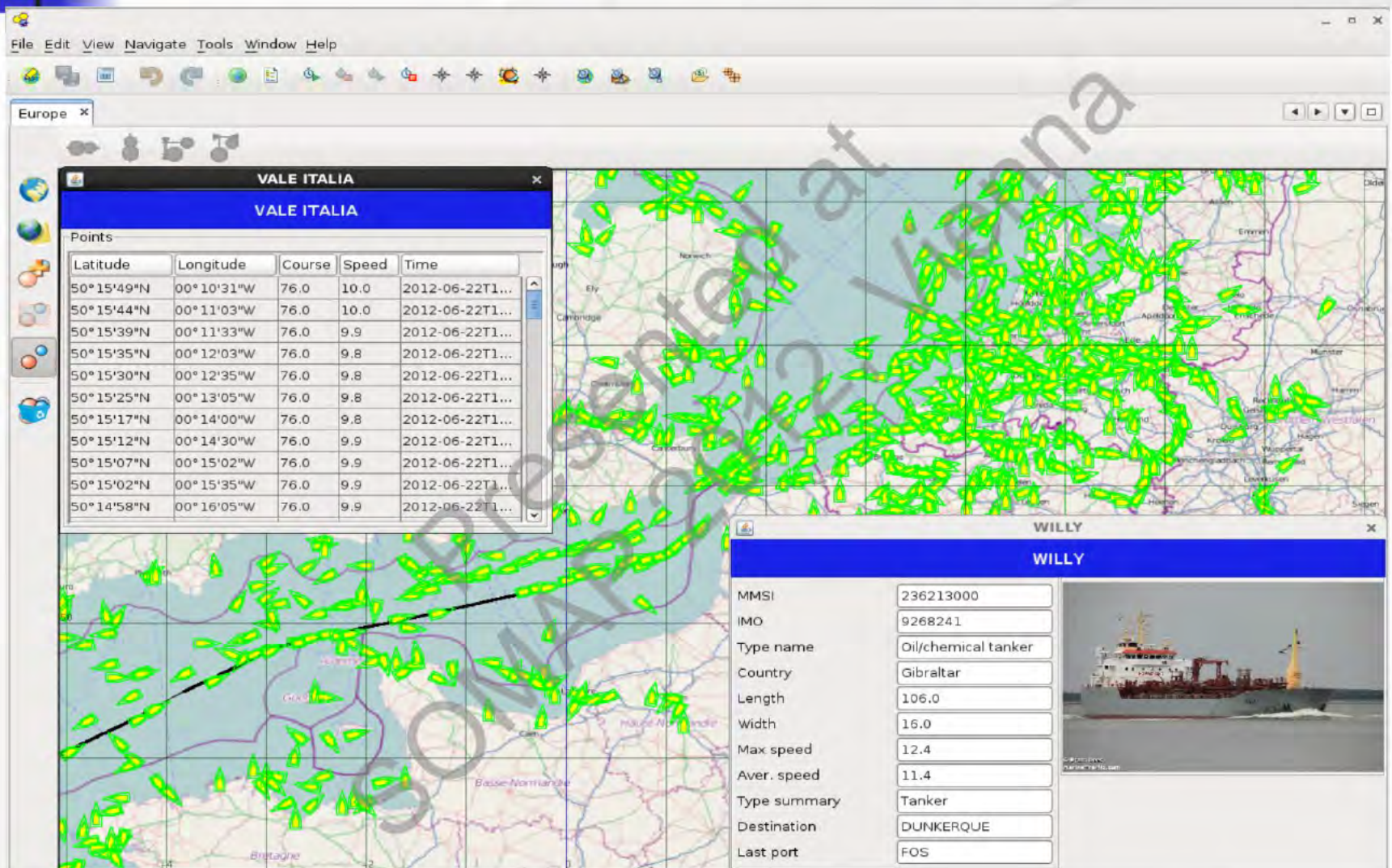
Generalized model of information fusion



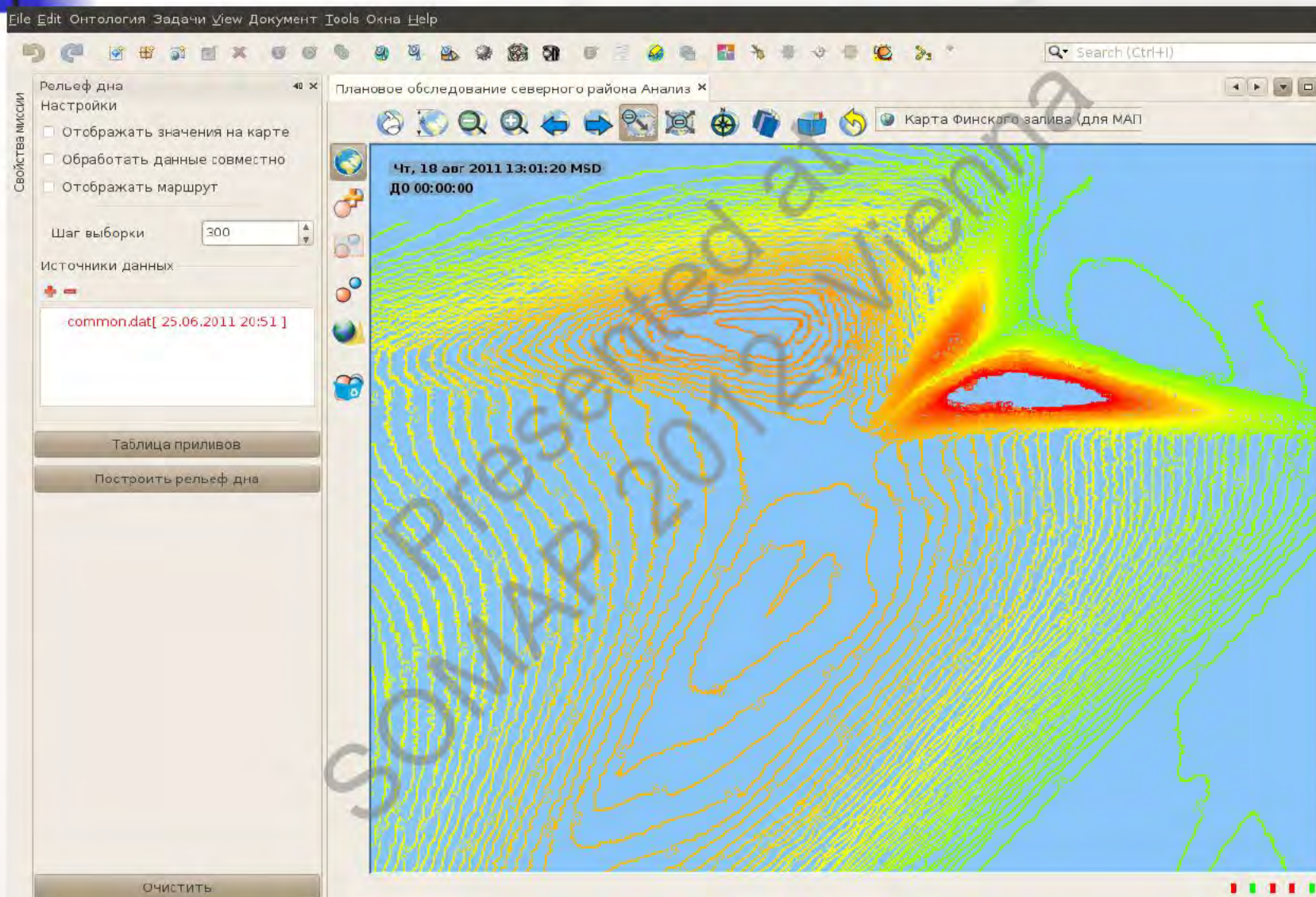
Cartographic data



Objects' data



Data received from external sources



Scenarios

The screenshot displays the SOMAP 2012 software interface, which is used for creating and editing scenarios. The interface is divided into several panels:

- Class Browser:** Located on the left, it shows a hierarchy of classes under the 'Sea' project. The 'Rule' class is selected, showing a list of rules including 'Breat Activity', 'Breat Status Start', 'Breat Subscenario', 'Breat Subscenario Action', 'Final AND Action Done', 'Final AND Join Done', 'Final AND Task Done', 'Final OR Action Done', 'Final OR Join Done', 'Final OR Task Done', 'Interim Action Done', 'Interim Task Done', 'Join Done', 'Join Task Done', 'Repeated Action', 'Repeated Task Action', 'Retract Second Join', 'Scenario Null', 'Start Scenario Command', 'Task Start', 'TC.Constant Bearing', 'TC.Create Bearing1', 'TC.Create Targets', 'TC.Dangerous Approach', 'TC.Dangerous Overtake', 'TC.Dangerous Towards', 'TC.Delete Bearing1', 'TC.Delete Old Target', 'vs.Action in many Schemes', 'vs.Action not in Scheme', 'vs.Decision in many Schemes', 'vs.Decision not in Scheme', 'vs.Display Report', 'vs.Empty final_actions', 'vs.Empty final_tasks', 'vs.Empty initial_actions', 'vs.Empty initial_tasks', 'vs.Final Action continues', and 'vs.Final Task continues'.
- Instance Browser:** Located in the top center, it shows the 's1.Collision' instance of the 'Rule' class, with an internal name of 'Sea_Class20046'.
- Scenario Scheme:** The main workspace, showing a flowchart of the scenario. The flow starts with a 'Start' node, followed by 'Use Decision', 'EqualKey/Value', 'MoreKey/Value', 'ObjectContainsObserver', 'IfActionStatus', 'IfActivityStatus', 'SignalControl', 'TC.Dangerous', 'EventFork', 'Flow', 'Task', 'Join', 's1.End Phase', 's1.Watch', 's1.Collision Handling Context', 's1.Collision Assessment', 's1.Near or Light', and finally 's1.Collision'. The flowchart includes various decision points and task nodes.
- TC.Constant Bearing:** A panel on the right showing the configuration for the 'TC.Constant Bearing' rule. It includes fields for 'Title', 'Dialect', 'Duration', 'Agenda-group', and 'Active'. The 'When' section contains a list of conditions, and the 'Then' section contains a list of actions.

The 'TC.Constant Bearing' rule configuration is as follows:

Title: TC.Constant Bearing

No-loop: ☐ **Auto-focus:** ☐

When:

```

f1: Bearing1( $l1: label, $l2: label2, $c1: course, $c2: course2, $s1: speed, $s2: bearing, $t: time1 )
DroClock: $sec: second -> ( $sec - $t > T.BNC_MN * 60 )
Target( title == $l1, $c3: course -> ( near( $c1, $c3, 2 ) ), $s3: speed -> ( near( $s1, $s3, 1 ) ), $l1: lat, $l2: lon )
Target( title == $l2, $c4: course -> ( near( $c2, $c4, 2 ) ), $s4: speed -> ( near( $s2, $s4, 1 ) ), $l2: lat, $l2: lon )
eval( near( $l1, $l2, 1 ) )

```

Then:

```

//System.out.println( "TC: " + $l1 + " " + $l2 + " " + $s1 + " " + $s2 + " " + $t );
float t = T_WARN_MAX.floatValue() / 60;
float w1 = $s1 * t;
float w2 = $s2 * t;
float[] p1 = Position.position( $l1, $l1, $c1, w1 );
float[] p2 = Position.position( $l2, $l2, $c2, w2 );
float[] kb1 = lineFromPoints( $l1, $l1, p1[1], p1[0] );
float[] kb2 = lineFromPoints( $l2, $l2, p2[1], p2[0] );
float[] xy = lineCross( kb1[0], kb1[1], kb2[0], kb2[1] );
float dist1 = distanceNM( $l1, $l1, xy[1], xy[0] );
float dist2 = distanceNM( $l2, $l2, xy[1], xy[0] );
float tim1 = dist1 / $s3 * 60;
float cat = 0;
if( tim1 < T_WARN_MAX )
{
String mess = String.format( "Bearings from %s on %s are constant, time to c
min", new Object[] { $l1, $l2, new Float( tim1 ) } );
if( tim1 <= 4 )
cat = 3;
else if( tim1 <= 8 )
cat = 2;
message( mess, cat );
retract( f1 );
}

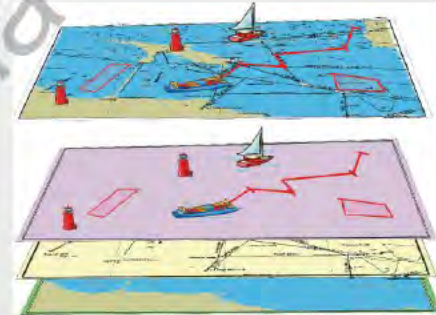
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Data Base, Knowledge Base, Ontology Services



Data base

Data base is multiplatform service-oriented software for centralized storage, selection and provision of geospatial information. DB services and ontologies are consumers of BD services



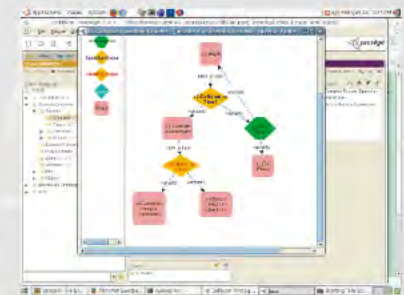
Ontology

Ontology service is a unified directory of information which is used to store the data needed to produce solutions to the problems faced by the user. It provides computer assisted formulation of the fundamental concepts and objectives of the knowledge domain and the relation between them. This component provides interaction not only between stored data but also data received from external sources.



Knowledge base

Services of **knowledge bases** provide with data necessary for functioning of the IGIS expert system component, which provides overall information-consulting and functional support to the user and the complex modeling modes.





End Users Services

Common services

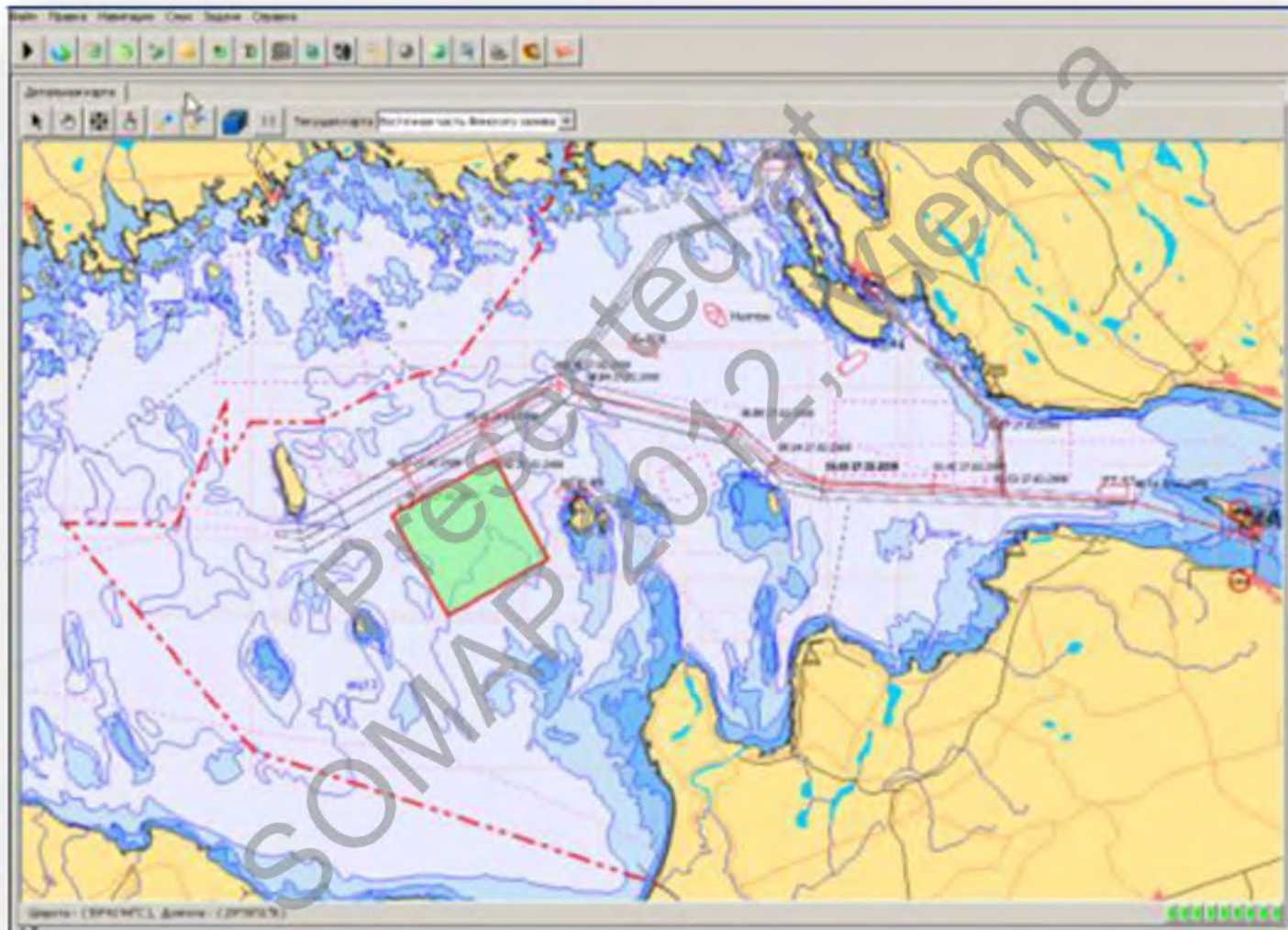
- Access to cartographic information
- Access to hydro meteorological information
- Mathematical problems modeling and solving (in theory of search, hydro acoustics, radio location, etc.)

Users' services of the objects' server

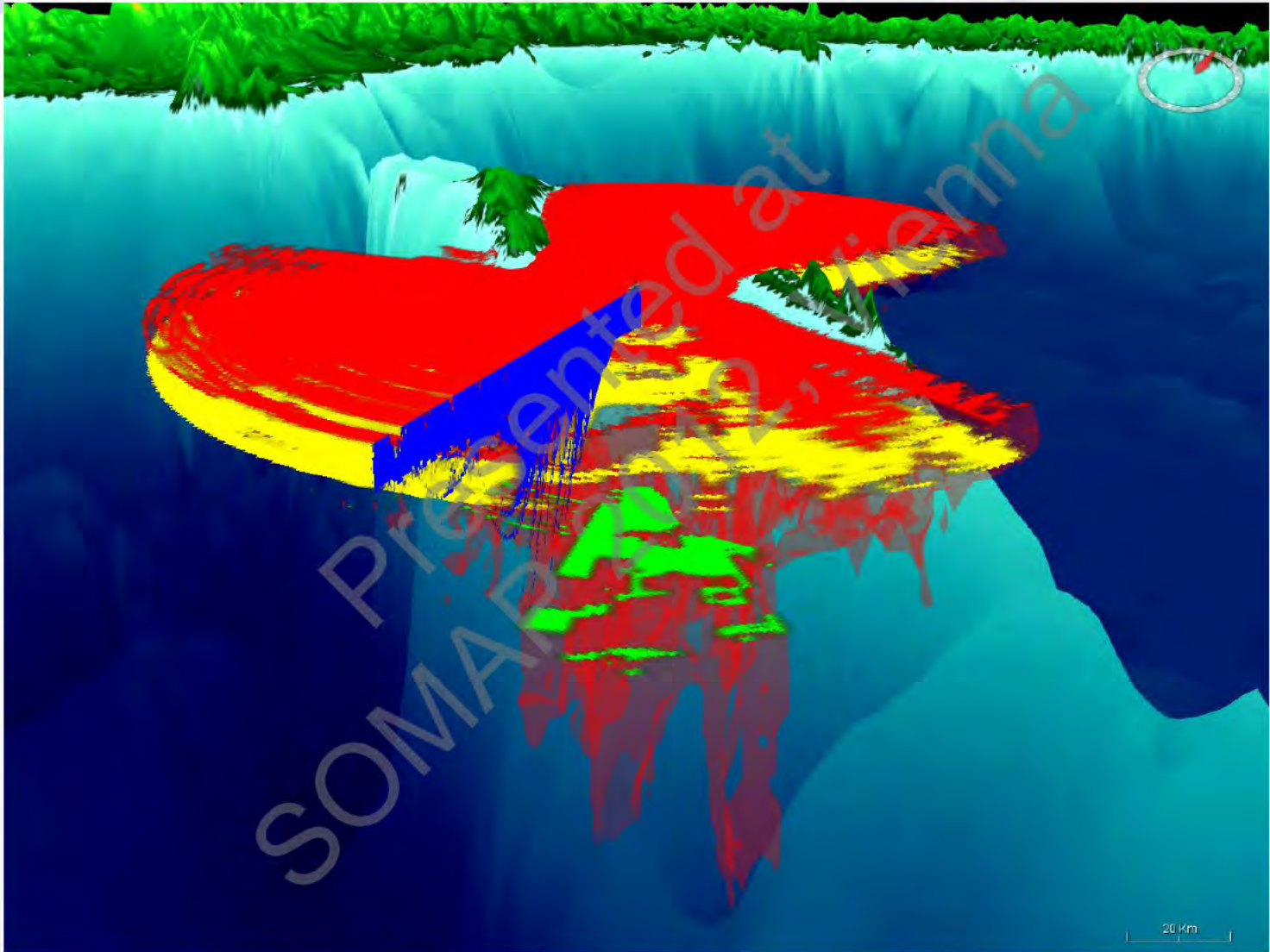
- Subject area universal description
- Inheritance mechanism also including a multiple inheritance of the objects
- Separation of the object's stationary and transient data
- Universal mechanism of relations
- Access to the history of the objects properties' states
- Information filtering for different users' groups

Case Study

Situation monitoring system



Case study. Acoustic fields calculation



Case Study

Underwater acoustics modeling system

Tasks	IGIS components
Input of source modeling data, including the geographic binding of acoustic energy source and receiver to the given space area	Cartographic information server and interaction with external systems server
Managing the access to geospatial data of environment parameters determining parameters hydro acoustic fields	Objects' server
Providing with modeling management interface and derivation/displaying of modeling results in the user-friendly form	User's interface
Interaction of hydro acoustic calculations subsystem with other IGIS components based on the uniform ontology.	Objects' server
Performing calculations providing for predictive estimate of source data that characterize environment (medium), realization of various methods and algorithms of acoustic field calculations	Mathematical models' server
Intelligent support of the calculations management that involves an identification of calculations' reference conditions, choice of rational method for acoustic field calculations; choice of methods enhancing calculations' efficiency and accuracy, methods of output data approximation, etc.	Expert system



Conclusions

IGIS architecture should support an execution of a number of requirements, the main ones are:

- convenient and well-defined access to data and information;
- flexible and fast applications' modification;
- fast integration of new applications into operating system;
- support of data standard formats;
- high degree of source code and other information resources reuse;
- dynamic expansion of system functions without additional programming and/or the whole project reprogramming;
- possibility of IGIS operation in local as well as in distributed environment.

Contacts

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